

QUIZ NO: 104

TOPIC: ELECTRICAL ENGINEERING

DATE: 31/08/2022

- 1. The starting torque of a 3-phase induction motor is ______ supply voltage ?
 - [A] Independent of
 - [B] Directly proportional
 - [C] Directly proportional to square
 - [D] Inversely proportional

Answer: C

Explanation:-

 $T_s = \frac{KE_2^2 R_2}{R_2^2 + X_2^2}$

 $E_2 = Rotor induced E. M.F$ per phase on standstill condition Which is directly proportional to applied volta

 $E_2 \propto V$

$$T_s = rac{KV_2^2R_2}{R_2^2 + X_2^2}$$

Hence $T_s \propto V^2$





- 2. The starting torque of an induction motor is maximum when rotor resistance per phase is _____ rotor reactance/phase ?
 - [A] Equal to
 - [B] Less than
 - [C] More than
 - [D] None of the above

Answer: A

Explanation:-

$$T_s = rac{K {E_2}^2 R_2}{{R_2}^2 + {X_2}^2}$$

On diffrentiating the above equation

$$\frac{dt}{dR_2} = K \left(\frac{1}{R_2^2 + X_2^2} + \frac{R_2(2R_2)}{\left(R_2^2 + X_2^2\right)^2} \right)$$

OnSolving

$$R_2{}^2 + X_2{}^2 = 2R_2$$

or

$$R_2 = X_2$$





Maximum starting torque is obtained when the slip is equal to the **ratio** between the **rotor resistance** (R_2) and the **rotor inductive reactance** (X_2). This slip is also known as slip at maximum torque, labeled as S_m .





3. The maximum torque of a 3-phase induction motor under running conditions is ?

[A] Inversely proportional to the Rotor reactance at standstill

- [B] Inversely proportional to the supply voltage
- [C] Directly proportional to the Resistance
- [D] None of the above

Answer: A

Explanation:-

The torque of rotor under running condition is

$$T=rac{K{
m s}{E_2}^2R_2}{{R_2}^2+{\left(sX_2
ight)}^2}$$

Slip Corresponding to Max torque

$$s = \frac{R_s}{X_s}$$

Putting the value of slip in above equation we get

$$T = rac{KR_2/X_2{E_2}^2}{{R_2}^2 + \left({R_2}^2/{X_2}^2
ight). {X_2}^2} = Krac{{E_2}^2}{2X_2}$$





Hence it can be concluded that the maximum torque 3 phase induction motor is inversely proportional to the rotor reactance.

The maximum torque is not dependent on the rotor resistance R_2 . But the slip at which it occurs i.e. the speed at which it occurs depends on the value of rotor resistance R_2 .

4. A 3 phase induction motor has the facility for pole changing from 4 to 6. When it is operating as a 4 pole machine on 440V, 50Hz balanced 3 Phase supply, the frequency of rotor current is 3Hz. Then the speed of the motor is ?

[A] 1500 RPM

[B] 1200 RPM

[C] 1360 RPM

[D] 1410 RPM

Answer: D

Explanation:-

Synchronous machine of 4 pole machine is Ns = 120f/p = 120×50/4 = 1500 RPM

Since Rotor frequency is slip times the stator frequency

<mark>fr =</mark> sfs

or s = fr/fs

= 3/50 = 0.06

Rotor Speed Nr = (1 - s) Ns



STATISTICS AND A STATIS



Nr = (1 – 0.06)1500

Nr = 1410 RPM

- 5. If the motor were to run at 65% speed as in 'the given above question, but operate as a 6 pole machine, what will be the slip and frequency of the rotor currents ?
 - [A] 4.175 Hz
 - [B] 3.286 Hz
 - [C] 2.458 Hz
 - [D] 1.432 Hz
 - Answer: A

Explanation:-

Synchronous speed of the 6 pole machine

Ns = 120f/p = 120×50/6 = 1000 Hz

N_{r2} = Rotor speed of 6 pole machine

= 0.65 × 141<mark>0 = 916</mark>.5 RPM

Slip s = $(N_{s2} - N_{r2})/N_{s2}$

s = (1000 - 916.5)/1000

= 0.0835

Rotor frequency fr = sfs





= 0.0835 x 50 = 4.175 Hz

6. For a slip of 0.05, find the ratio of rotor speeds with the motor operating with 4 and 6 poles respectively ?

[A] 2.8

[B] 1.5

[C] 3.2

[D] 4.5

Answer: B

Explanation:-

Rotor speed with 4 poles with slip 0.05

= (1 – 0.05)×1500 = **1425 RPM**

Rotor speed with 6 poles with slip 0.05

= (1 - 0.05)1000 = **950 RPM**

The Ratio of rotor speeds with the motor operating with 4 and 6 poles

 $N_{r4}/N_{r6} = 1425/950 = 1.5$





- 7. Semi-closed slots or totally closed slots are used in induction motors to improve ?
 - [A] Starting current
 - [B] Starting Torque
 - [C] Power Factor
 - [D] Pull-out Torque

Answer: C

Explanation:-

Semi-closed slot in an Induction motor

Advantages

- Semi-closed slots have narrow slots, therefore, flux distribution is uniform hence harmonics are less so smooth operation is possible.
- In the Semi-closed slot, the average length of the air gap is less compared to the open type hence magnetic circuit reluctance is the less magnetizing current means better power factors.

Disadvantages

- It is not possible to insert large former coils.
- Access to the slot is difficult compared to an open type.
- They offer high leakage reactance to the windings.

Closed slots have almost same advantages and disadvantages.





- 8. The rotor slots are slightly skewed in squirrel cage induction motor in order to?
 - [A] Increasing Rotor bar strength
 - [B] Prevent cogging effect
 - [C] Both 1 & 2
 - [D] None of the above

Answer: B

Explanation:-

- Rotor bars are skewed to prevent the cogging effect.
- When an induction motor refuses to start even if the full voltage is applied to it, this is called cogging.
- Starting torque of an induction motor depends on the product of the magnitude of stator and rotor current and sine of the angle between both.
- If the conductors remain linear, the angle between stator and rotor current will be 180 degrees. As sin(180)=0, the starting resultant torque will be zero and thus motor will fail to start. This phenomenon is called cogging.
- Skewing makes the rotor conductor longer with the reduced cross area. This increases the rotor conductor resistance hence starting performance and the torque of an induction motor are improved.
- 9. A 3-phase induction motor is running at 2% slip. If the input to rotor is 1000 W, then mechanical power developed by the motor is ?
 - [A] 500 W
 - [B] 200 W
 - [C] 20 W
 - [D] 980 W

Answer: D

Explanation:-





Mechanical power developed in 3-phase motor = $(1 - s) \times power$ input to rotor

= (1 – 0.02) x 1000 = 980 W

10. The approximate efficiency of a 3-phase, 50 Hz, 4-pole induction motor running at 1350 r.p.m. is ?



